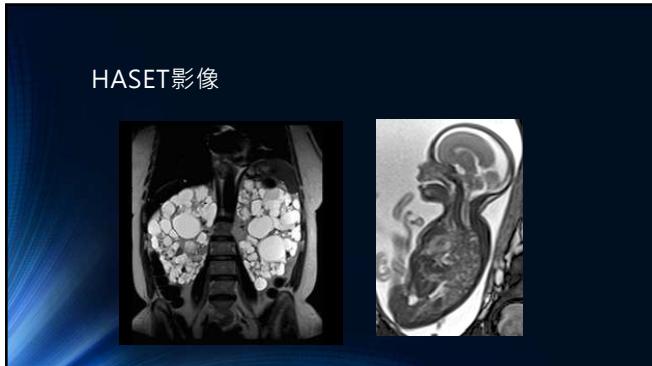


Gradient echo sequence(梯度回訊序列)

- 小於 90°的 RF
- 沒有180°的 RF 重聚相
- 短TR、短TE · 用於快速造影
- 運用 Bi-lobed Gradient 進行重聚相
- SNR較低
- 對於磁敏感假影(susceptibility artifact) 較敏感

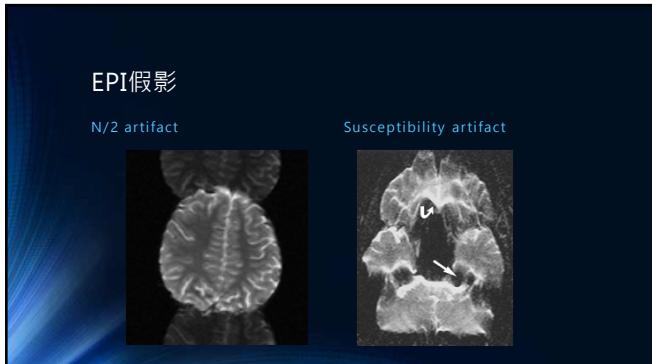
HASTE

- *Half-Fourier Acquisition Single-shot Turbo spin Echo imaging*
- 在一次激發下取得影像(**single-shot technique**)
- ETL很長.....問題又出現了.....
- 訊號的特性--- 360°相位變化 · 正、負半波對稱
- 只取正半波 · 複製成負半波(一半再多一些...)
- PE下降 · SNR降低
- 用於快速造影



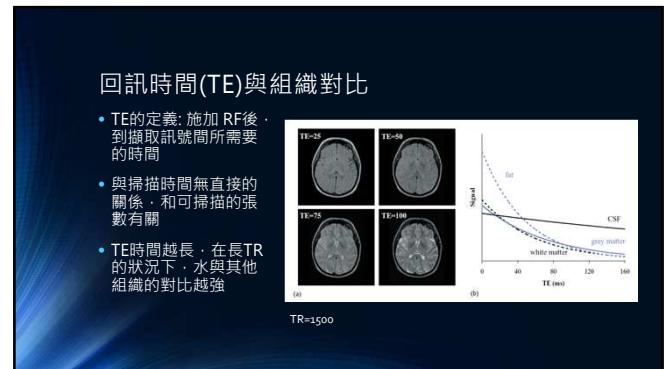
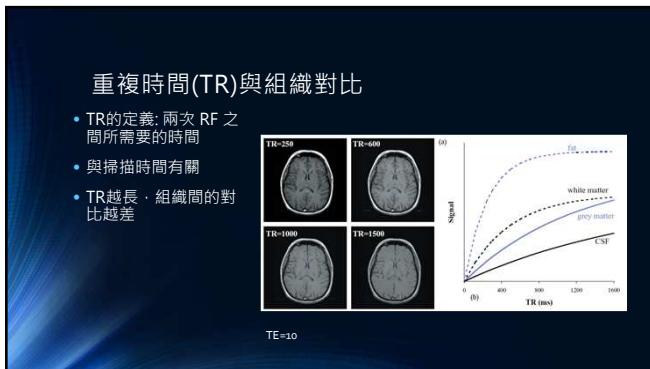
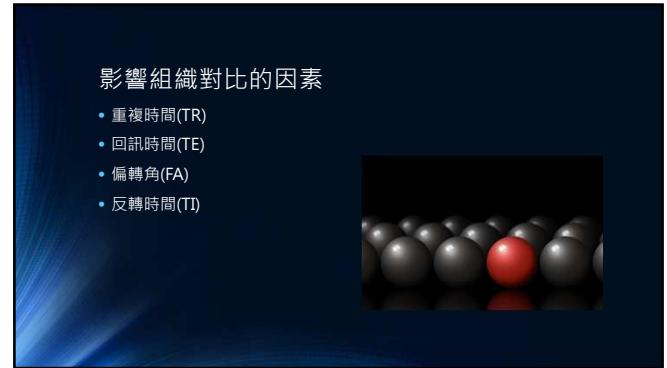
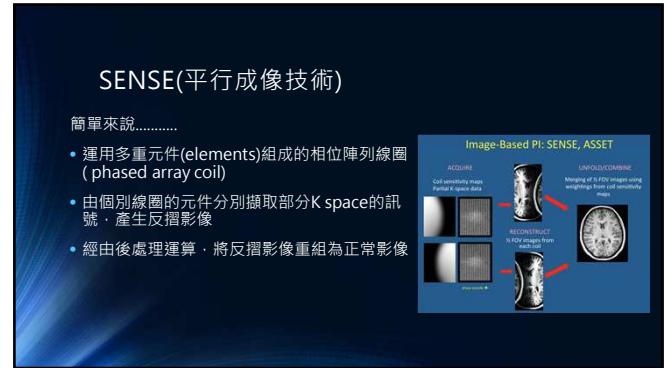
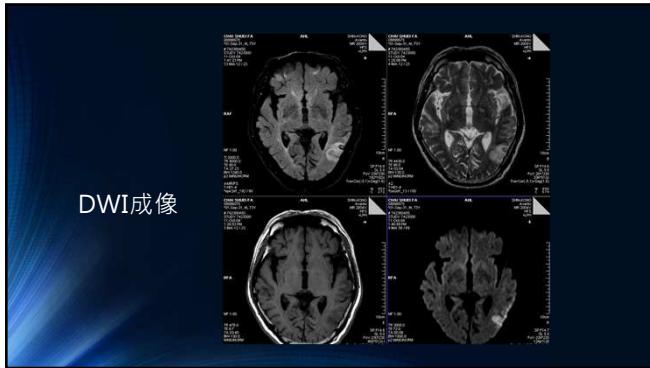
EPI (Echo-Planar Imaging)

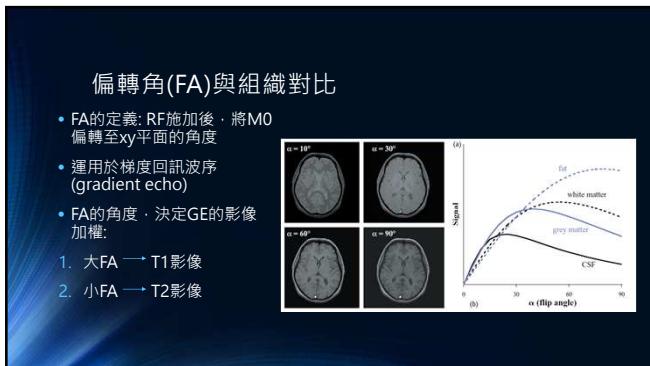
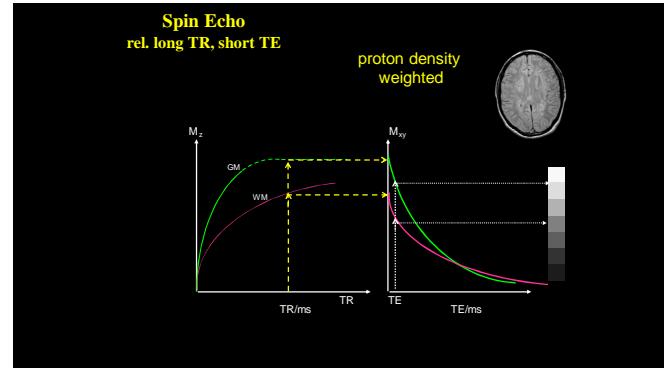
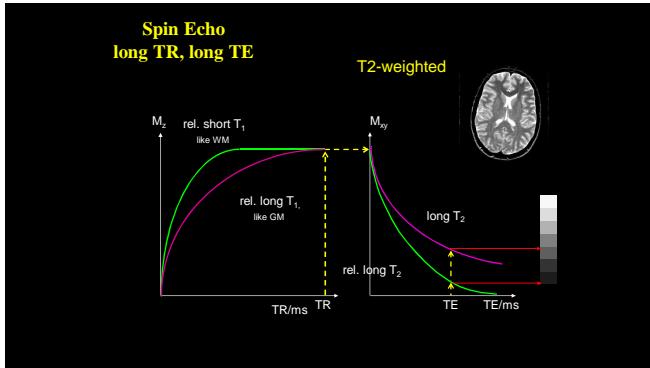
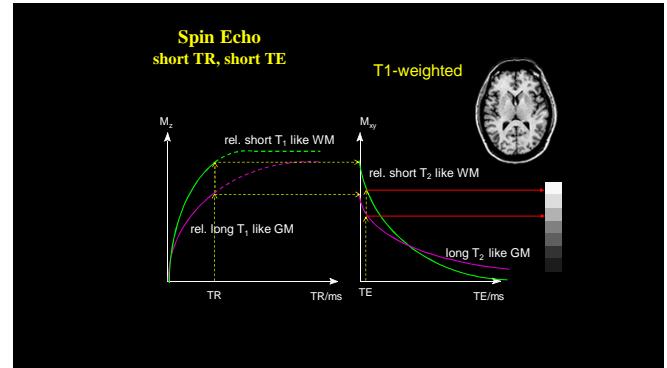
- 運用梯度磁場的快速轉換
- 在一次的激發中完成影像的攝取
- 超快速成像
- 易產生下列假影:
 1. N/2 artifact
 2. Susceptibility artifact
 3. Chemical shift artifact

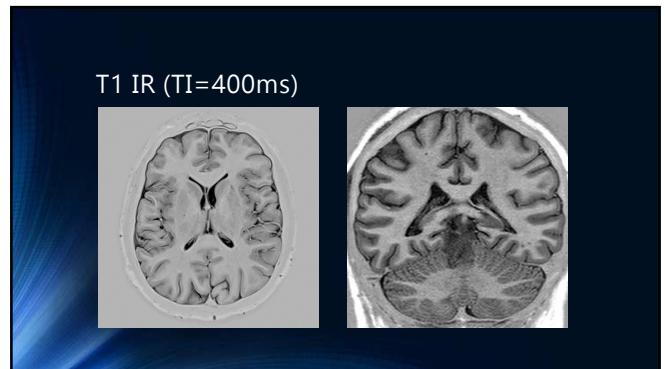
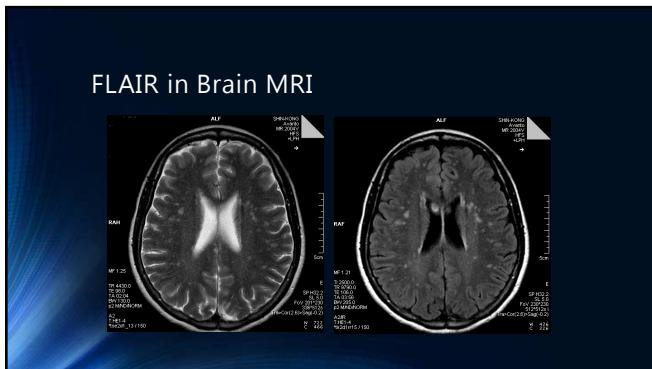
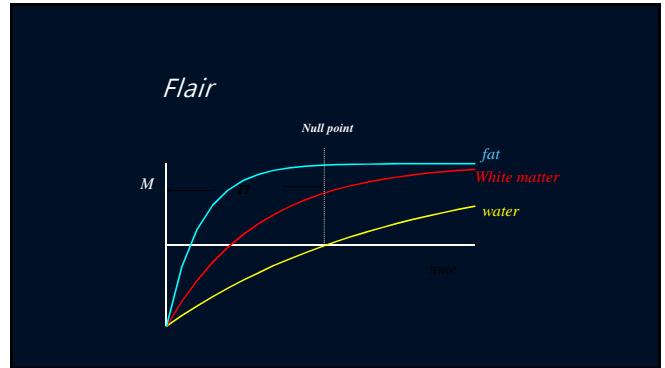
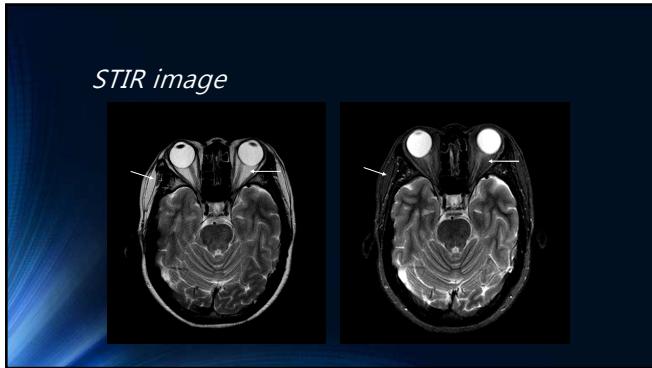
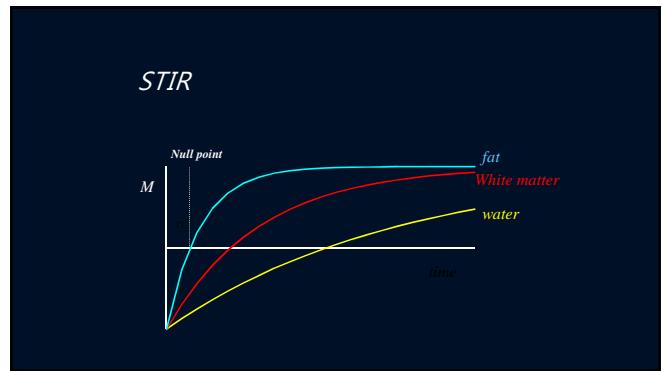
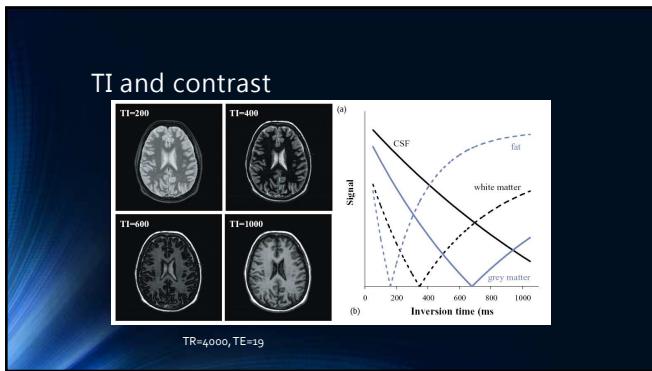


EPI 在臨床上的應用

- Diffusion imaging of the brain.
- Dynamic perfusion studies of the brain.
- Abdominal imaging.
- Cardiac imaging:
 1. Coronary arteries
 2. Cine cardiac imaging within a single heart beat.
 3. Dynamic perfusion studies of the myocardium.







Signal to Noise Ratio(訊雜比)

Signal(訊號)	Noise(雜訊)
<ul style="list-style-type: none"> 影像中像素或體素中的相對亮度 與物質中的氫原子密度有關 	<ul style="list-style-type: none"> 影像中隨機出現的雜點 多數由病患組織中產生

影響SNR的因素

- 重複時間(TR)
- 回訊時間(TE)
- 體素大小
- 平均次數(NSA)
- 切面厚度
- 頻寬

TR, TE 與SNR

- 重複時間(TR)
 - TR越長 · SNR越高(下次可偏轉到xy平面上的越多)
- 回訊時間(TE)
 - TE越長 · SNR越低(訊號衰減越多)

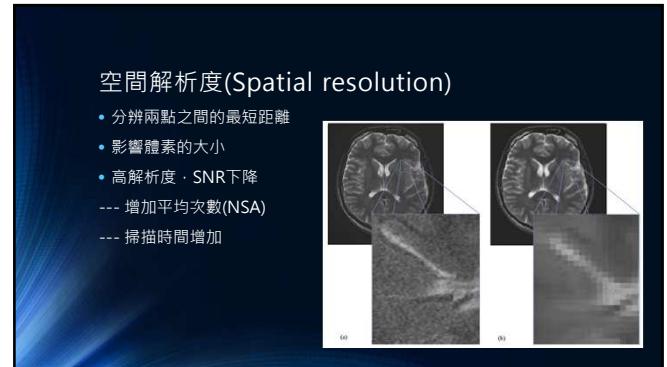
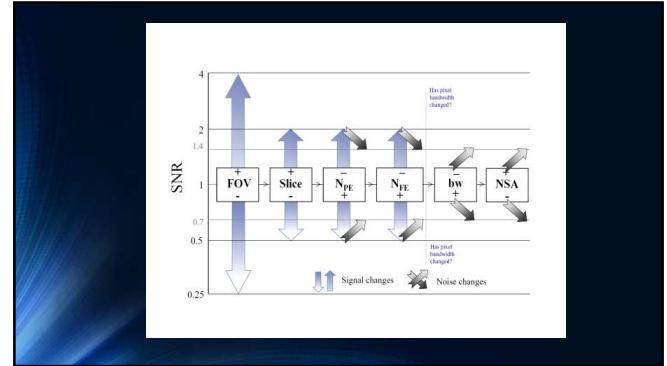
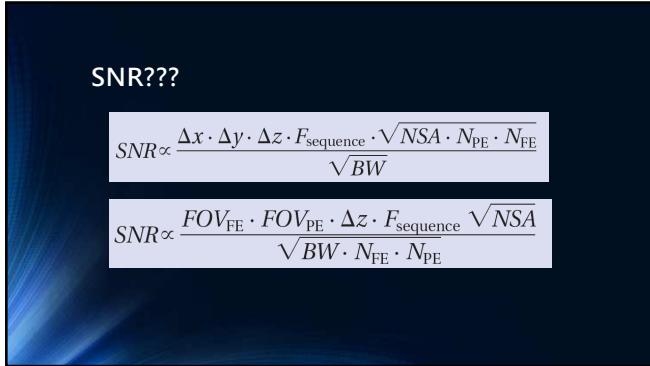
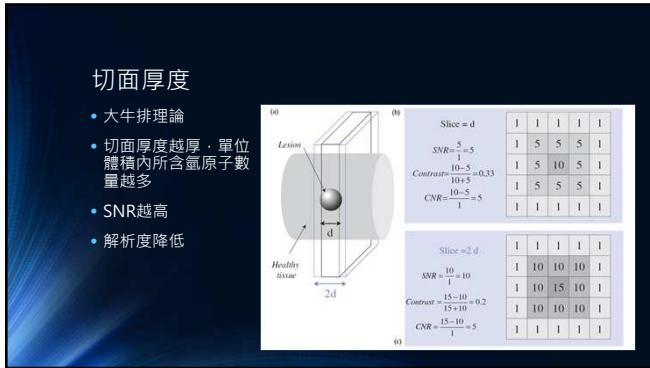
體素大小 (Voxel size)

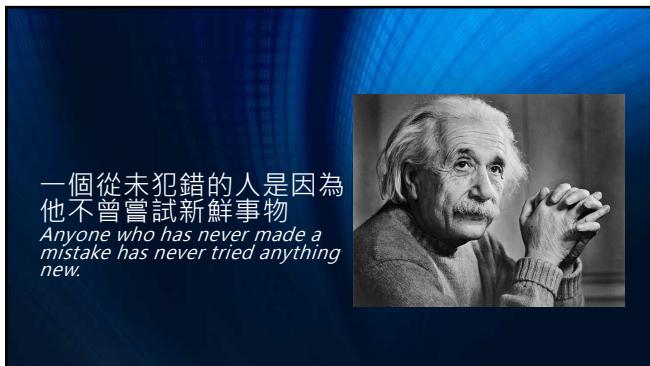
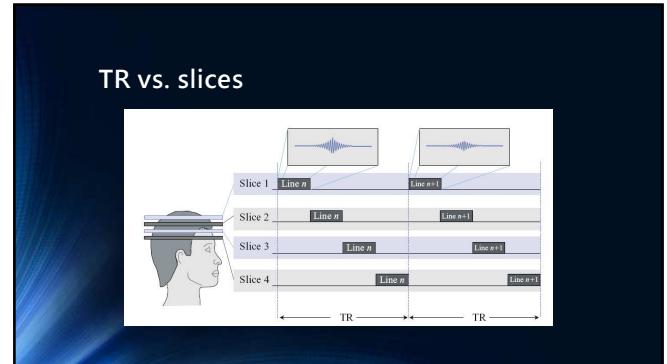
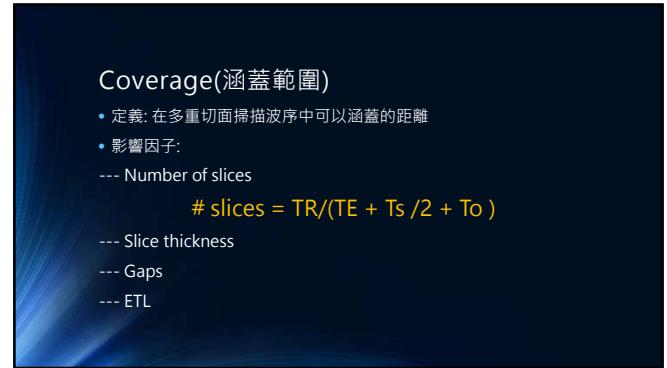
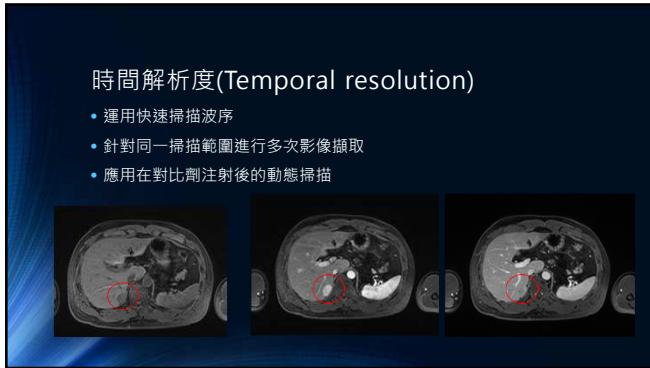
- 大牛排理論
- 體素越大 · 單位體積內所含氫原子數量越多
- SNR越高

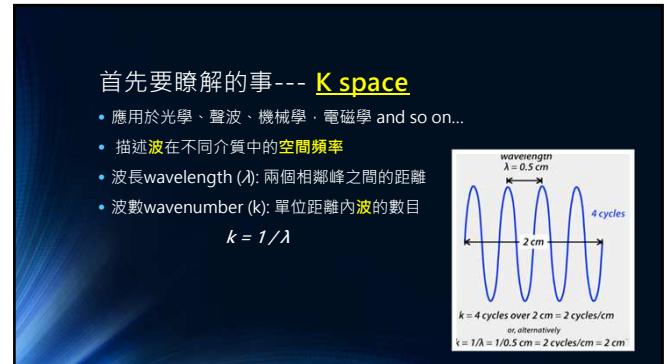
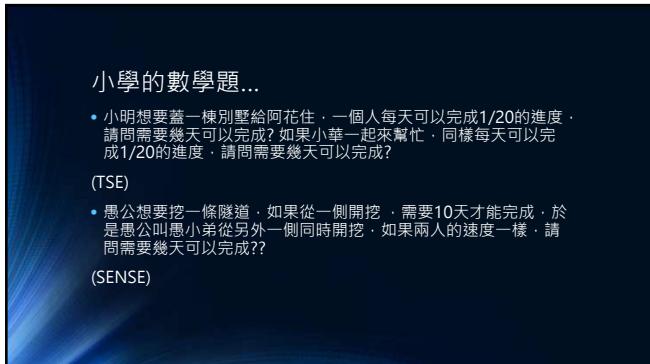
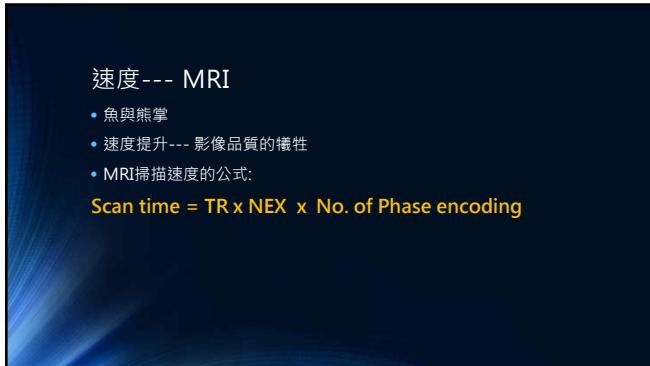
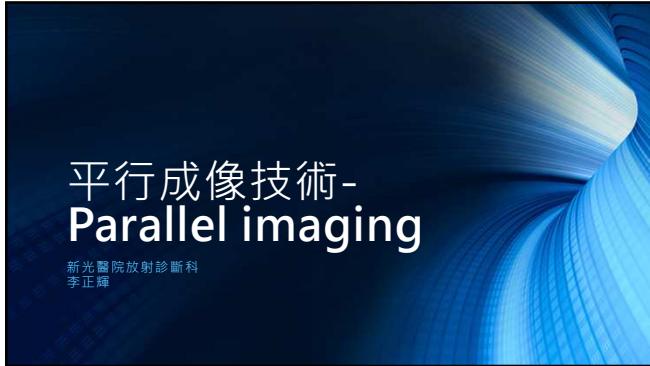
Voxel size

平均次數(NSA)

- 針對特定區域內組織 · 訊號重複擷取的次數
- 擷取的次數每增加一倍 · 相位編碼的次數也增加一倍
- 所需Scan time 加倍 · SNR增加 $\sqrt{2}$ 倍







空間頻率(Spatial Frequencies)

- 單位距離內的波數
- 空間頻率高，單位距離內的波數多
- 可分辨兩點間的距離縮短
- 高解析度(Resolution)
- 以 line pairs per mm 為單位

MRI vs. K space ???

- MRI的訊號--- 一系列的 sine 和 cosine 波組成
- 一度空間---線，二度空間---平面
- 平面訊號必須由各個不同的方向進行運算

也就是說.....

- 經由電腦的後處理(傅立葉轉換)，影像可以被分解成具有不同相位(phase)、頻率(frequency)、振幅(amplitude)與方向性(orientation)的訊號集合
- K space
- 影像的空間諧波含量
- 諧波特性的集合

K space 中不同位置所包含的資訊??

- 中央部分---低頻資訊(low spatial frequency information)
- 包含影像的對比、亮度以及外形
- 外圍部分---高頻資訊(high spatial frequency information)
- 包含影像的邊界、細節以及銳利度

空間編碼

- 藉由不同強度與方向性的梯度磁場組合
- 利用磁度磁場產生的訊號頻率
- 將"位置"的訊號特性進行擷取
- 包含三個重要的編碼方向：
- 切面選擇(Slice selection)
- 相位編碼(Phase encoding)
- 頻率編碼(Frequency encoding)

切面選擇(Slice selection)

- 決定所需擷取的切面位置與厚度
- 施加梯度磁場
- 只激發特定的頻寬內的氫原子核

頻率編碼(Frequency encoding)

- 運用梯度磁場
- 依據所定義的取樣間隔
- 將訊號進行區隔並讀出
- 頻率編碼次數---解析度

相位編碼(Phase encoding)

- 訊號的來源
- 藉由相位的改變，將所得到的訊號，填入K space中特定的位置
- 相位編碼次數越多，訊號越好
- 每次改變相位並填入 K space 所需的時間--- TR
- 掃描時間 = TR x NEX x 相位編碼的次數**
- 決定整體掃描時間的重要因素

常規成像技術 vs. 平行成像技術

- 常規成像技術(以TSE為例，ETL=16)

掃描時間 = (TR x NEX x 相位編碼的次數) / (ETL)

TR=3000ms、NEX=1、相位編碼的次數=256、ETL=16

Scan time= 48000ms = 48s
- 平行成像技術

掃描時間 = (TR x NEX x 相位編碼的次數) / (ETL x 加速因子)

Scan time= 48000ms/2 = 24s

加速因子--- 藉由減少**相位編碼**的次數，降低掃描時間

關於平行成像技術

- 運用多重元件(elements)組成的相位陣列線圈(phased array coil)

- 較大的單一元件(element)線圈相較於多重元件(elements)組成的相位陣列線圈接收較多的雜訊
- SNR 提升

關於平行成像技術

- 傳統上使用相位陣列線圈(phased array coil)中，各獨立的元件(element)接收訊號並組成最終的影像
- 每一獨立元件(element)依其位置的不同對訊號的接收效率也有所不同---線圈敏感度(Coil sensitivity)

關於相位陣列線圈(phased array coil)

- 為表面線圈(surface coil)的一種(具訊號接收功能，但通常不具RF發送功能)
- 由多個表面線圈組合而成
- 保留小線圈的sensitivity，但可涵蓋較大範圍的掃描空間

關於平行成像技術

- 減少相位編碼的次數(under sampling)
 - > 減少掃描時間
- 產生反摺假影(warp-around artifact)
- 影像重建(reconstruction)
- > 傅立葉轉換後(image domain)進行的重建 :SENSE, mSENSE
- > 傅立葉轉換前(frequency domain)進行的重建 :SMASH, GRAPPA

影像的重建

The “Unfolding” Problem in Parallel Imaging

Folded/wrapped data from each coil
+
→
a b c d → a b c d → a b c d → a b c d

How to get from this... To this... To this

傅立葉轉換後(image domain)進行的重建

- SENSE(SENSitivity Encoding)
 - > 最先發展的平行成像技術
 - > 藉由跳躍式進行相位編碼的方式以減少影像擷取的時間
 - > 取得反摺的影像
 - > 運用 coil sensitivity 的資訊(Reference images)將反摺影像重組
 - > 完成無反摺假影的影像

SENSE 成像(加速因子=2)

Acquired FOV
Reconstruction FOV
C1
C2
y y + ΔY
 $I_d(y) = C_1(y) S(y) + C_1(y + \Delta Y) S(y + \Delta Y)$
 $I_d(y) = C_2(y) S(y) + C_2(y + \Delta Y) S(y + \Delta Y)$

SENSE 作用的四個步驟

- 產生 coil sensitivity map
- 取得部分 K space 的 MR data
- 從個別得線圈中重建部分 K space 的 MR data
- 藉由矩陣的反推運算解反摺並組成影像

Image-Based PI: SENSE, ASSET

ACQUIRE
UNFOLD/COMBINE
RECONSTRUCT

Reference images and Aliased images

(a) (b) (c) PE

mSENSE(Modified SENSE)

- 不另外產生Reference images
- 在取正常診斷用影像時，在K空間的中央部分額外取數條訊號
- 此額外取得之訊號由各獨立之線圈(or element)分別取得
- 產生低解析度、無反摺之影像作為Reference images

傅立葉轉換前(frequency domain)進行的重建

- SMASH (SiMultaneous Acquisition of Spatial Harmonics)
- Auto-calibrating SMASH
- Variable density Auto-SMASH (VD-Auto-SMASH)
- GRAPPA (GeneRalized Autocalibrating Partially Parallel Acquisitions)

SMASH (SiMultaneous Acquisition of Spatial Harmonics)

- 第一代的平行成像技術
- 作用在 K space 的層面
- 藉由發送RF並接收相關的空間資訊，產生一組與真實訊號相似的假性 k-space 相位編碼訊號
- 也就是說，在適當的運用來自不同線圈元件的信號的組合，以產生均勻(相加)或不均勻(相減)的空間頻率
- 同時使用coil sensitivities 來產生不同權重的組合

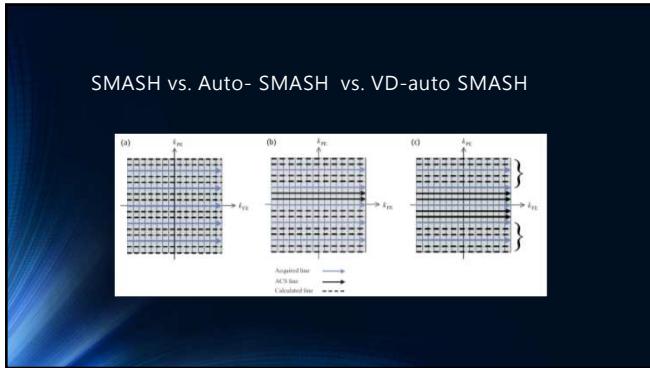
結合梯度改變與線圈相位編碼排列在3次訊號攝取中產生6條Kspace lines

Auto-calibrating SMASH

- 取得部分 K space 的 MR data
- 在接近中心部分取得 auto-calibrating signal' (ACS) lines
- 計算最接近 ACS 的 K space 訊號並與ACS 訊號進行對比
- 將所得到的有效參數結果套用到其他取得的部分 K space MR data中

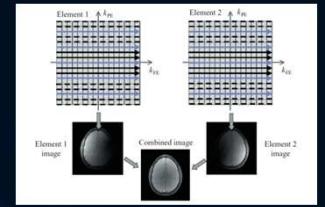
Variable density Auto-SMASH (VD-Auto-SMASH)

- 在中心部分取得更多的 auto-calibrating signal' (ACS) lines
- 減少假影(artifacts)及重組時的錯誤
- 相較於Auto-calibrating SMASH · scan time 較長



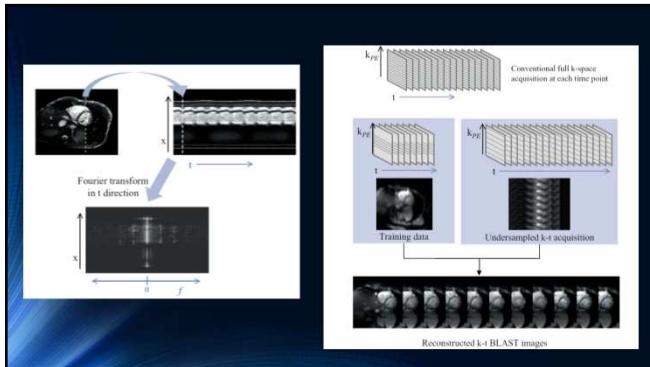
GRAPPA (GeneRalized Autocalibrating Partially Parallel Acquisitions)

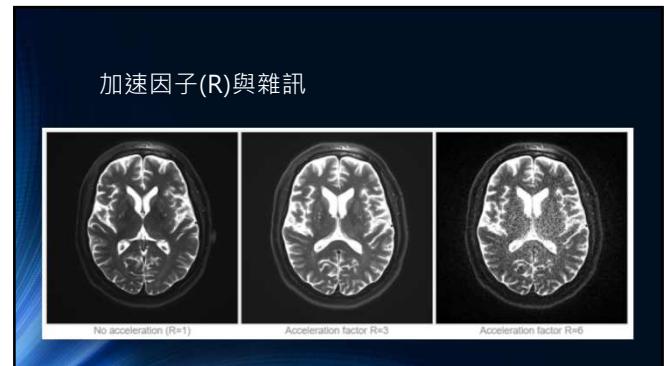
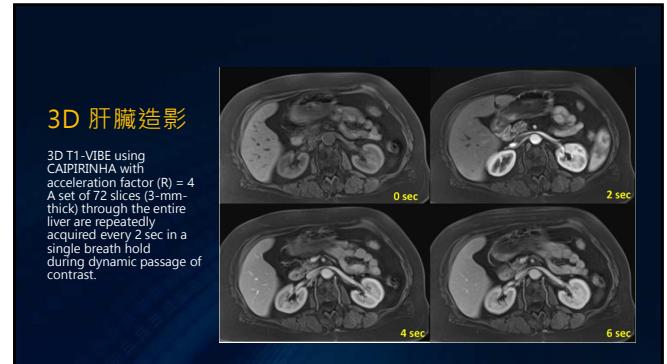
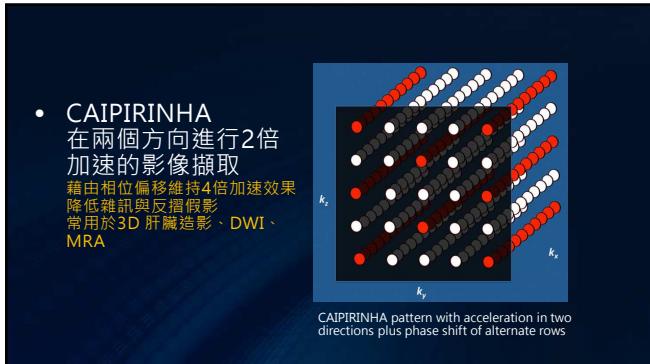
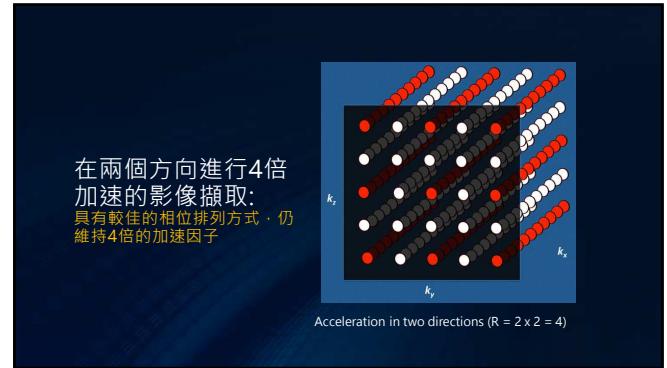
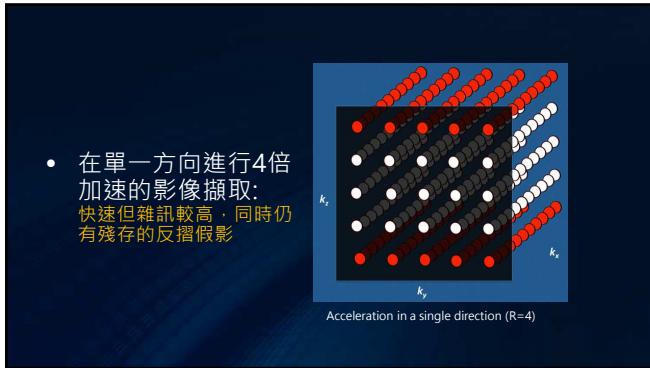
- Auto-SMASH 進階版
- 由個別線圈各自產生獨立的 ACS line
- 各自對個別線圈所產生的訊號進行校正並進行重組

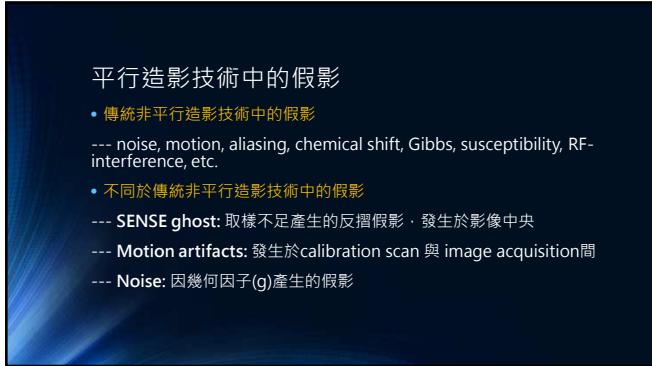


k-t BLAST (Broad-use Linear Acquisition Speed-up Technique)

- 運用於單一切面中的動態造影(dynamic techniques)
- 原理: (以心臟動態造影為例)
 - 胸壁、肺臟、脊椎、肌肉等組織在造影過程中並無太大變化
 - 偷懶一下.... 周圍組織只做一次，只針對移動的心臟進行完整掃描
- 快速、高時間及空間解析度
- 可與SENSE技術結合，實施快速、多切面、高時間及空間解析度造影
- Training data: 一組低解析度的連續影像(只要幾張就夠了...)







平行造影技術中的假影

- 傳統非平行造影技術中的假影

--- noise, motion, aliasing, chemical shift, Gibbs, susceptibility, RF-interference, etc.

- 不同於傳統非平行造影技術中的假影

--- SENSE ghost: 取樣不足產生的反摺假影，發生於影像中央

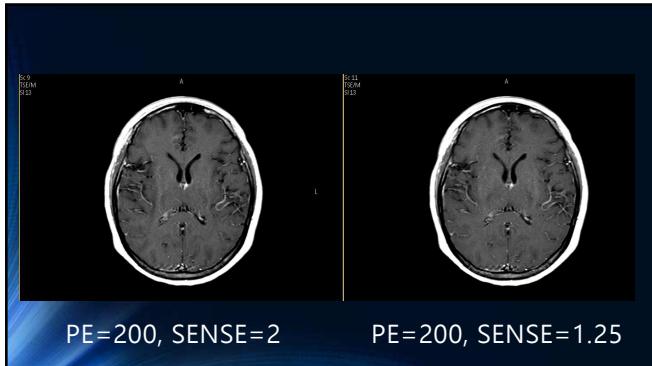
--- Motion artifacts: 發生於calibration scan 與 image acquisition 間

--- Noise: 因幾何因子(g)產生的假影



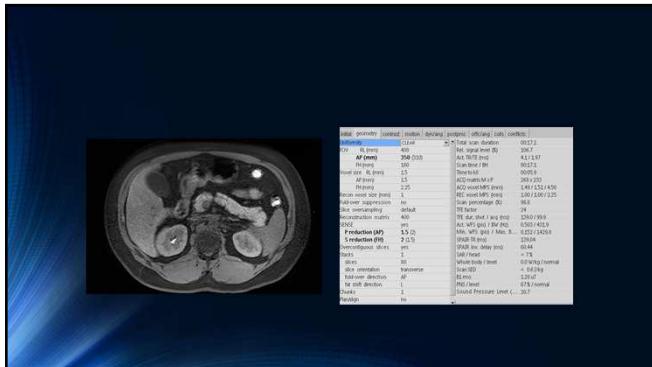
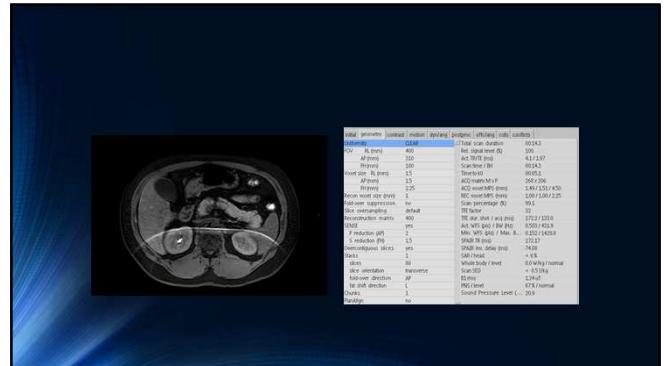
SENSE ghost

- 加大FOV
 - Over Sampling
 - 降低加速因子(R)



PE=200, SENSE=2

PE=200, SENSE=1.25



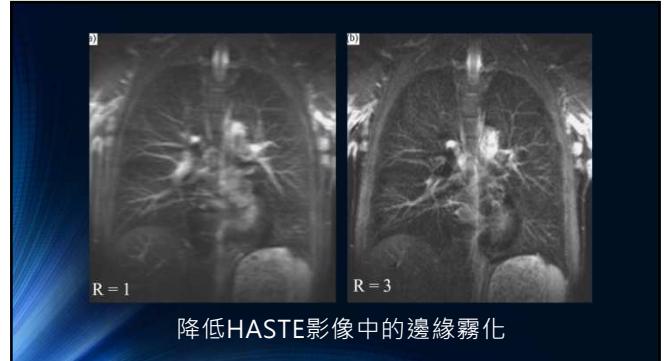
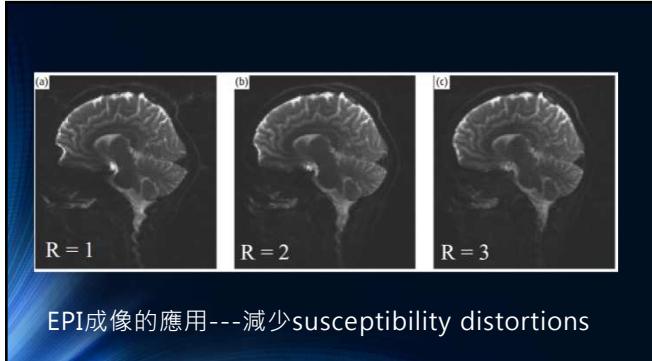
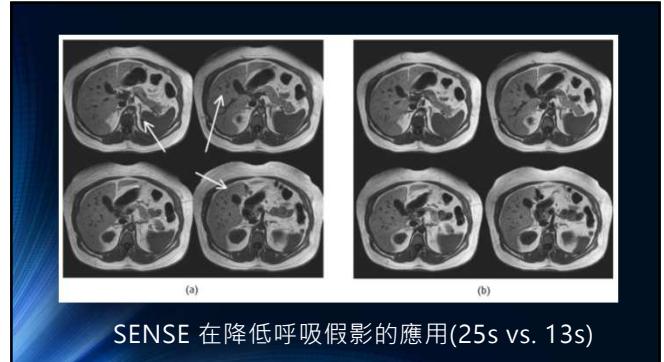
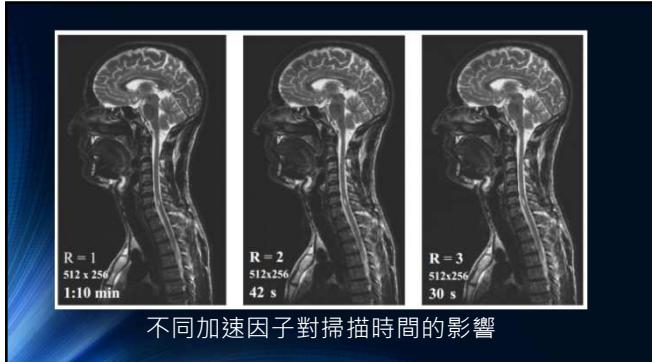
Motion artifacts

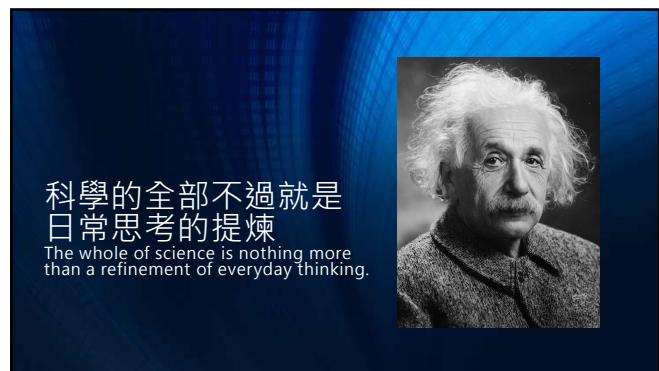
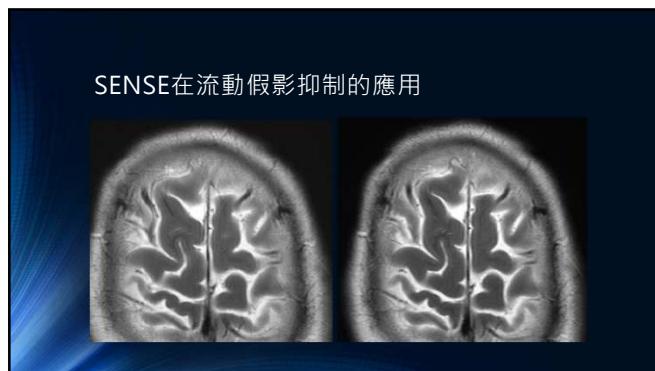
- 常見於高訊號組織(FAT)
 - 重新固定病患後再次執行掃描
 - 使用自動校準平行加速技術(mSENSE)

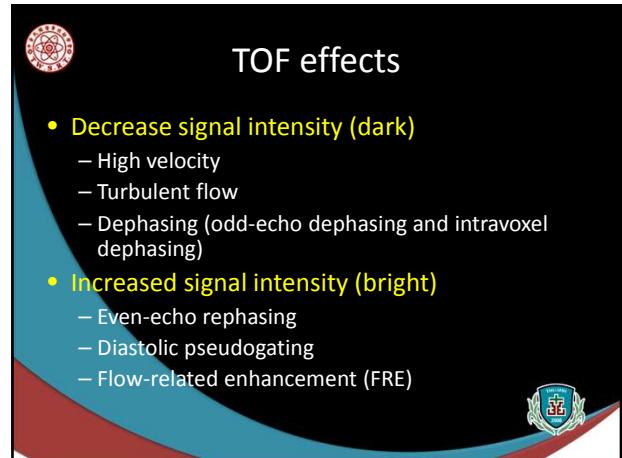
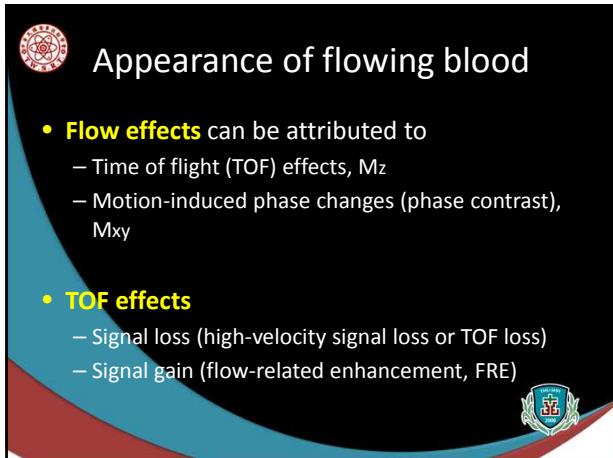
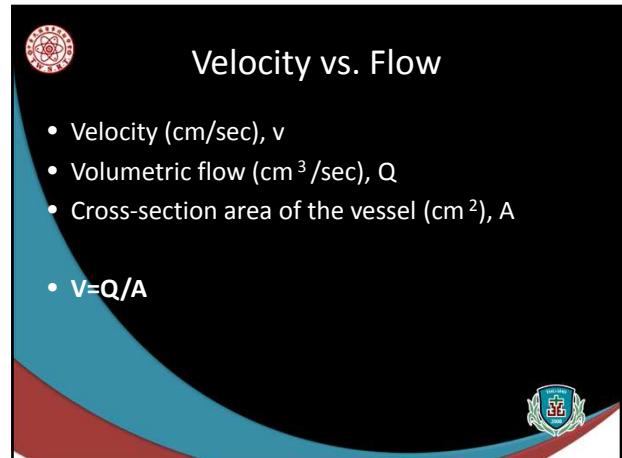
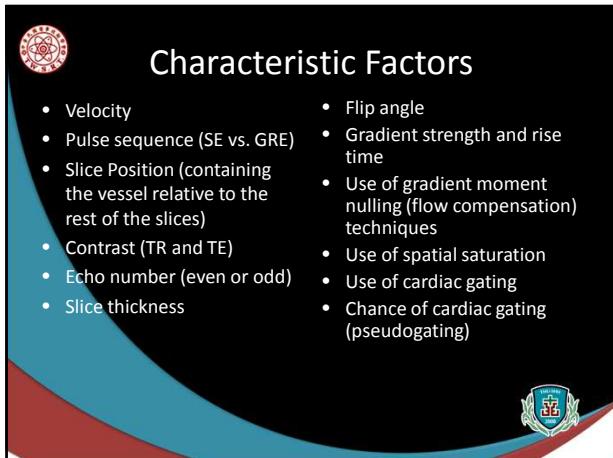
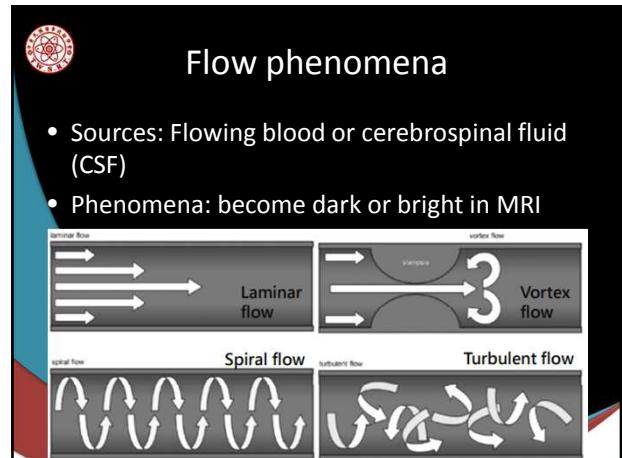


平行造影技術在臨床使用的優勢

- 減低掃描時間
- 降低氣時間減少 · 降低移動假影
- 合理時間內取得高解析度影像
- EPI成像的應用
- 縮短echo train length (increasing the PE bandwidth)
- 減少susceptibility distortions
- 降低HASTE影像中的邊緣霧化(減少echo spacing)







High velocity signal loss

- **Spin echo** imaging
- Slice-selective refocusing RF

$$I \propto \left(1 - \frac{v}{2\Delta z}\right) \times 100\%$$

$$V_m = \frac{\Delta z}{1/2 TE}$$

Velocity (v) and phase (ϕ)

$$\phi = \int \omega dt = \int (\gamma G v t) dt = \gamma G v \int t dt = \gamma G v (t^2/2)$$

- Phase and velocity are proportional
- A quadratic relationship exists between phase and time $\phi = kt^2$

Echo number effects

Time	Phase
RF/Echo 0	0
90°	$k\tau^2$
TE/2 = τ	$-k\tau^2$
1st echo	$2k\tau^2$
TE = 2τ	$-k(2\tau)^2$
180°	$3k\tau^2$
3rd echo	$7k\tau^2$
TE = 3τ	$-k(3\tau)^2$
2nd echo	$5k\tau^2$
4th echo	$-7k\tau^2$

Echo number effects

- Assume velocity of blood flow is **constant**
- Odd echo \rightarrow dephasing \rightarrow signal decrease
- Even echo \rightarrow rephasing \rightarrow signal gain

Diastolic pseudogating

- Systole (rapid) vs. diastole (slower)
- In diastolic, the TOF effects result in higher intravascular signal.
- Use cardiac gating to acquire slice at a fixed point in the cardiac cycle.
– $TR = 1/(\text{heart rate})$

Flow-related enhancement (FRE)

- **Gradient echo**
- Entry phenomenon
- The fresh inflowing blood that enters the first slice is totally un saturated (by last RF excitation)

$$I \propto I_0 + \left(\frac{TR}{\Delta z}\right)v$$

$$V_m = \Delta z/TR$$

Cocurrent Flow

- The slice excitation wave (SEW) is in the direction of successive 90 deg. Excitation pulses.
- If flow is perpendicular to the slice.....

Countercurrent Flow

- If flow is perpendicular to the slice.....

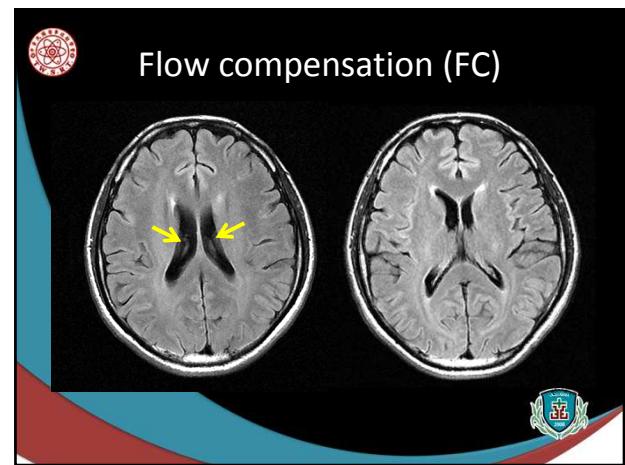
Flow compensation (FC)

- Gradient moment nulling (GMN) : can minimize flow artifacts
- Add extra gradient pulses to produce the even-echo rephasing effect on the first echo
 - 1st-order FC : Constant velocity
 - 2nd-order FC : Constant acceleration
 - 3rd-order FC : Turbulent (jerk) flow
- Can be applied to all the three coordinates
- FC lobes lengthen the TR/minimum TE

Flow compensation (FC)

- 1 2 1 gradient lobes (constant velocity)

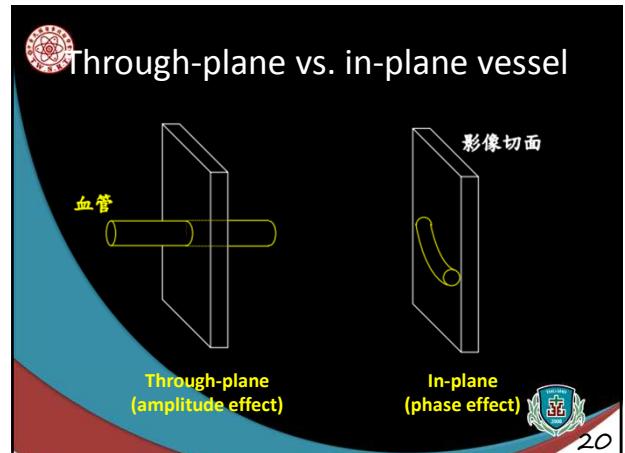
Flow compensation (FC)



Unenhanced MRA

- Rely solely on flow effects (the movement of blood)
- Amplitude effects (through-plane flow)
 - Blood flowing into or out of a chosen slice has a different **longitudinal magnetization (M_z)** compared to stationary spins.
 - Depend on the duration of stay (time-of-flight; TOF) in the slice
- Phase effects (in-plane flow)
 - Blood flowing along the direction of a magnetic field gradient changes its **transverse magnetization (M_{xy})** compared to stationary spins.

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Flow-related signal enhancement

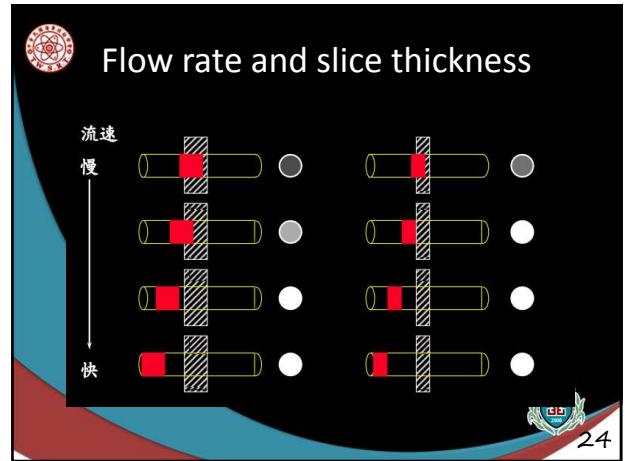
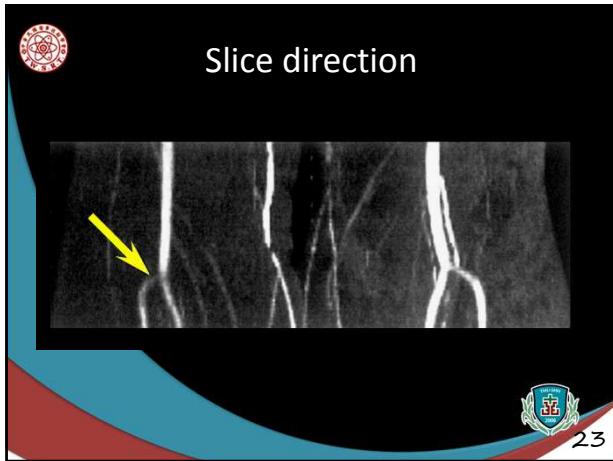
- The FRE occurs **both with SE and GRE** sequences.
- The competing **TOF loss in SE** tends to overbalance the FRE at higher flow velocities, leading to decreased flow signal.
- **TOF angiography**
 - GRE sequences
 - Bright-blood images

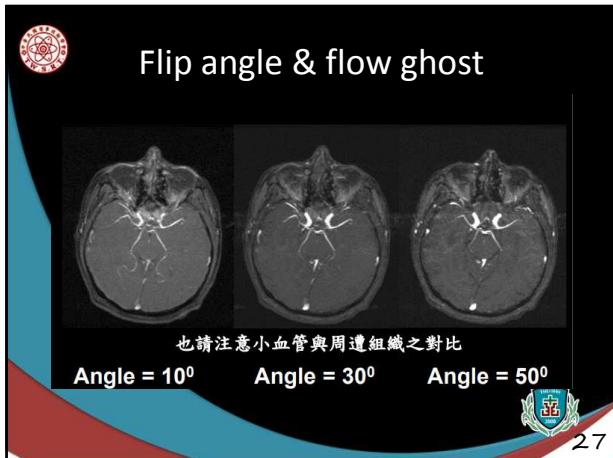
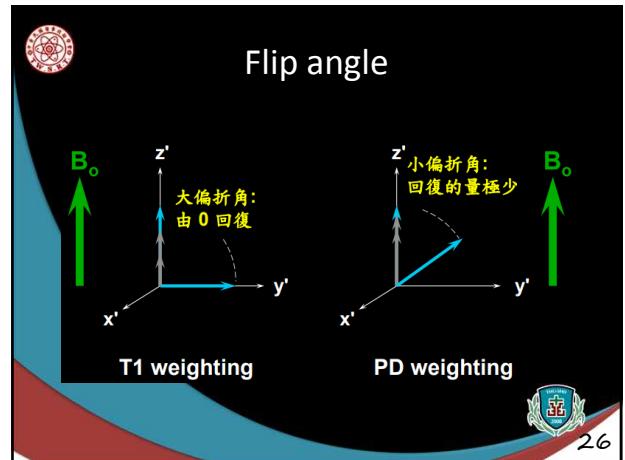
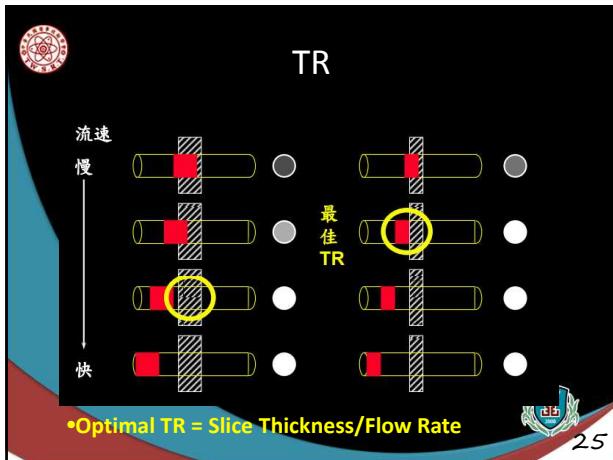
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Factors affect FRE

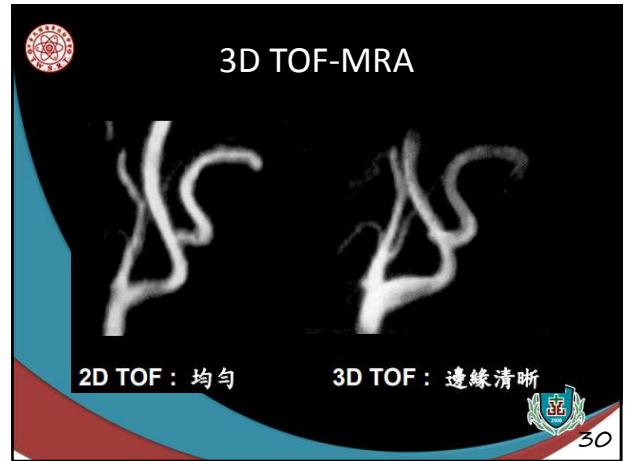
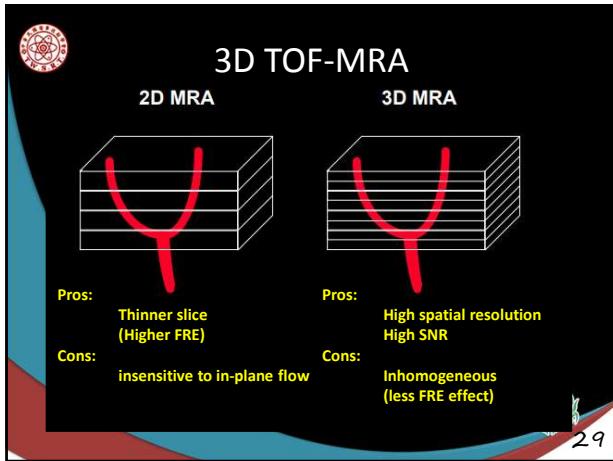
- Through-plane or in-plane flow (slice direction)
- Ratio between flow rate and slice thickness
- TR
- Flip angle

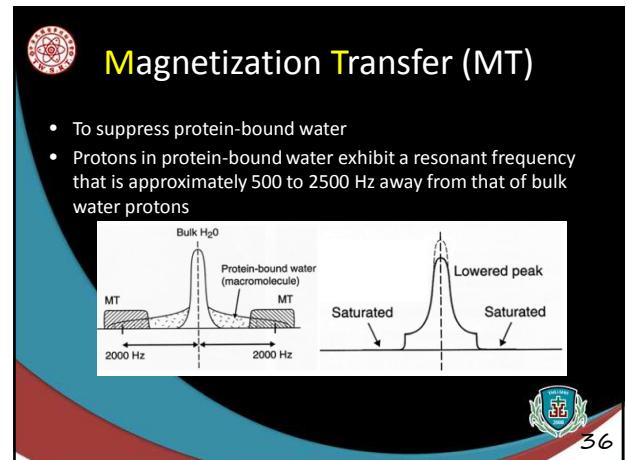
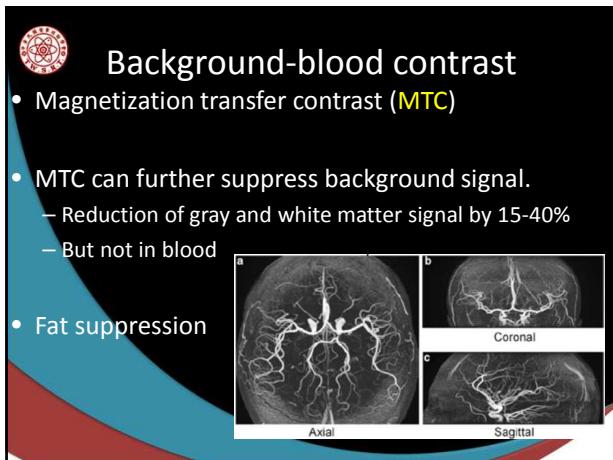
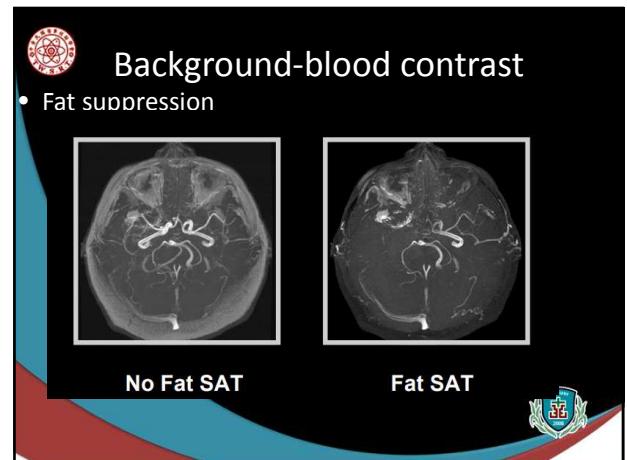
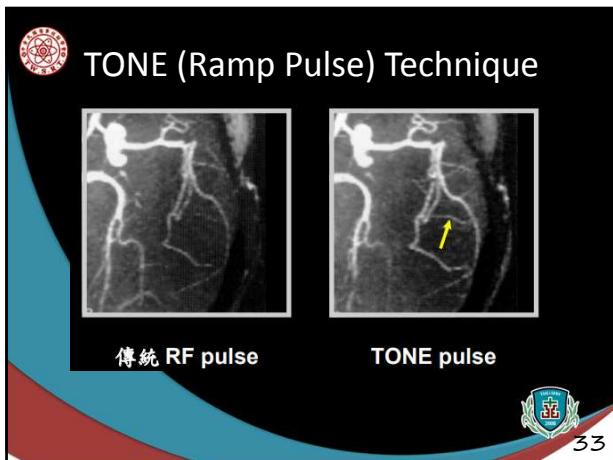
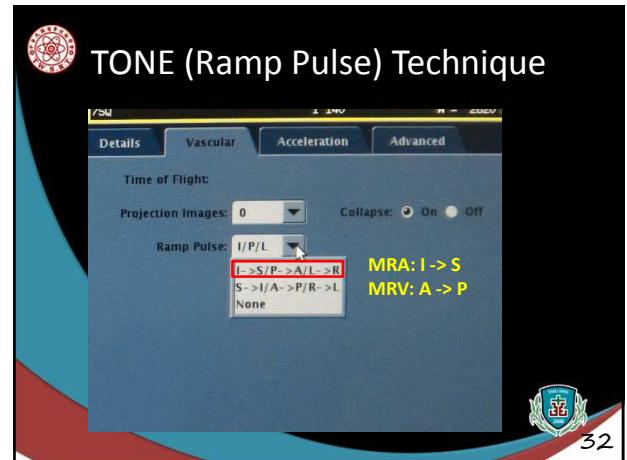
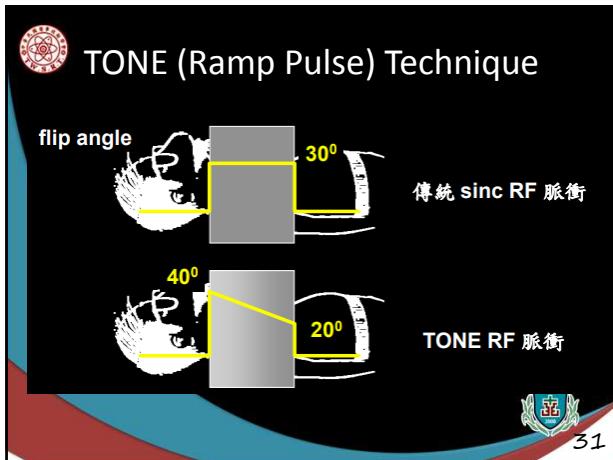
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- **Spoiled GRE sequences (SPGR)**
 - No TOF loss phenomenon
 - **Short TR** (< 5 msec) to reduce spin dephasing
 - Short acquisition time to acquire 3D datasets
 - **Flow compensation** (refocus unwanted phase accumulations)
- TOF techniques can be divided into 3 groups
 - Sequential 2D multi-slice method
 - 3D single-slab method
 - 3D multi-slab method





Magnetization Transfer (MT)

- MT is similar to spectral fat suppression techniques except that here, the off-resonant frequency is up to 2000 Hz as opposed to 220 Hz in the case of fat suppression.
- Used in time of flight (TOF) MRA to suppress the background brain tissue and enhance visualization of smaller vessels

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Spatial saturation pulse

- Superior saturation pulses are used to suppress the signal from veins above the heart, and arteries below the heart
- Inferior saturation pulses are used to suppress the signal from arteries above the heart and veins below the heart

Sequential 2D technique

- Larger flip angle (30 deg.~70 deg.)
- Thicker slice thickness (2~3 mm) to achieve better SNR
- Best suited for imaging vessels that are straight and perpendicular to the slices.
 - Carotid arteries or vessels in the lower extremities.
- It is necessary to synchronize the acquisition of data to the cardiac cycle (**ECG gating**).

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3D multi-slab method

- Presaturation slab above the imaging volume suppresses the signal of venous flow.

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TOF-MRA & MRV

Phase effects

- Phase effects concern the **transverse magnetization**.
- Apply a pair of gradients with identical strength and duration but opposite sign (**bipolar flow-encoding gradient**).
- Stationary spins → zero net phase shift
- Flowing spins → a non-zero phase shift

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Phase contrast method

- A direct quantitative measure of the velocity of the flowing blood
- No restriction on image orientation (not dependent on inflow effects)
- Velocity encoding (VENC)**
 - The velocities between $-VENC$ and $+VENC$ are encoded by the phase shifts between -180° and $+180^\circ$.
 - The flow velocity exceeded the VENC value \rightarrow aliasing
- General velocity**
 - Arterial flow 40~60 cm/s
 - Venous flow 20~30 cm/s

Phase contrast method

- Phase-encoded images

Phase contrast = Enhance 3D Velocity

Phase contrast (Example. 1)

3D TOF
L't VA occlusion???

Phase Contrast (sag.)
VENC = 25

TOF – MRA
Stenosis????

TOF – MRA (Change direction)
Stenosis????

Phase Contrast (axi.)
VENC = 25

TOF vs. phase contrast MRA

	TOF-MRA	Phase contrast MRA
Advantages	Simple to implement, robust High spatial resolution Shorter acquisition time (in 3D)	No saturation effects Excellent background suppression Enables quantitative flow measurement
Disadvantages	Reduced sensitivity to slow flow Restrictions to size and orientation of the imaging volume Short T1 tissue may be mistaken for flowing blood	Prior knowledge about flow rates Very long acquisition times for 3D techniques Susceptible to phase errors



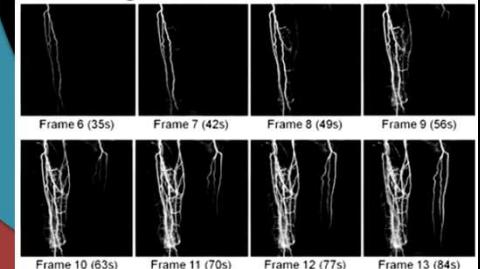
Contrast-enhanced MRA

- Avoidance of blood signal saturation
- Better turbulent flow imaging
- Injection a contrast material intravenously (IV) to selectively shorten the T1 of the blood → brighter signal in T1W images.
- Gadolinium-chelate (Gd) contrast agents
 - Seven unpaired electrons → paramagnetic, shorten T1 and T2
 - Injection rate: 0.5~4.0 ml/s
 - Injection volume: 0.1~0.3 mmol/kg body weight, typically 20~40 ml
 - Computer-controlled power injector
 - Examine the patient's renal function before scanning!



Contrast-enhanced MRA

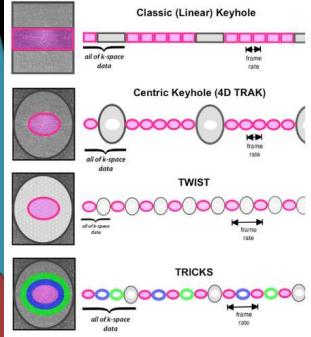
- 3D, RF-spoiled, fast gradient-echo imaging sequences → T1W images (FSPGR, FLASH)







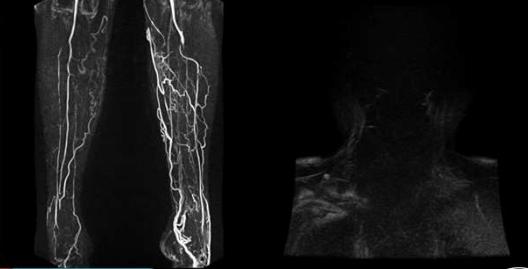
Time-Resolved MRA



- Keyhole imaging.
- Siemens: TWIST (Time-resolved angiography With Stochastic Trajectories)
- GE: TRICKS (Time-Resolved Imaging of Contrast KineticS)



Time-Resolved MRA





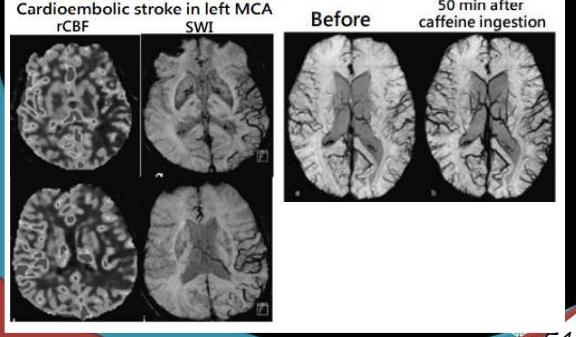


Susceptibility Weighted Imaging (SWI)

- SWI is an MR technique that utilizes the magnetic susceptibility differences
 - Visualize small veins in the brain
 - Microbleed
 - Sensitive to iron & calcification



Susceptibility Weighted Imaging (SWI)







History of SWI

- Originally proposed by Reichenbach et al. as "MRV" or "BOLD venographic imaging"
 - Small vessels in the human brain: MR venography with deoxyhemoglobin as an intrinsic contrast agent. Radiology, 1997.
- Haacke et al. 2004
 - Susceptibility weighted imaging (SWI)



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Magnetic Susceptibility

- When an object is placed in an external magnetic field H , magnetization is induced in the object.
- Magnetic susceptibility is the magnetic response of a material when it is placed in a magnetic field.
 - $M = \chi H$
 - χ = susceptibility (ppm)
 - M = induced magnetization
 - H = applied field
- If diamagnetic, $\chi < 0$
- If paramagnetic, like deoxygenated blood, $\chi > 0$



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Image Acquisition

- High-resolution 3D gradient echo imaging with 3-direction flow compensation
 - Long TR
 - Long TE (~ 40 ms at 1.5T, ~ 25 ms at 3.0T) to get T_{2*} weighting
- Utilize both magnitude and phase images
- GE: SWAN, Siemens: SWI

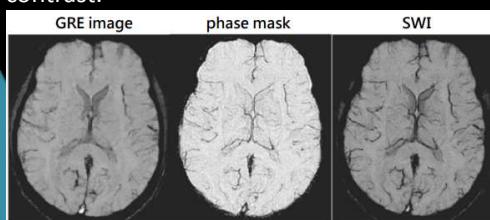


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SWI vs. conventional GRE

- The use of the filtered phase to enhance contrast.

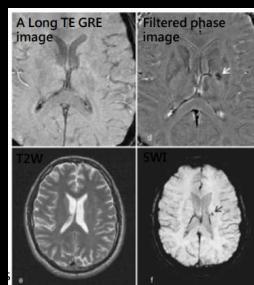


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SWI vs. conventional GRE

- Tissues that have very low and uniform iron distribution will show a phase effect, but not a T_{2*} effect.
 - Without phase dispersion \rightarrow no T_{2*} effect.



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SWI processing

- Acquire high-resolution 3D GRE with flow compensation.
- Apply HPF to phase image to obtain SWI filtered phase data.
- Create phase mask depending on sign.
- Multiply phase mask by original magnitude image to obtain "merged SWI magnitude data."
- Perform a minimum intensity projection (mIP) over neighboring slices



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